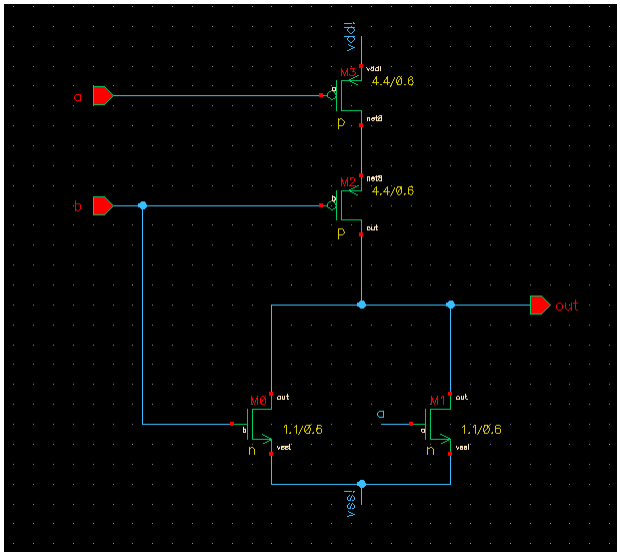
CS/EE 5710/6710

Layout

Basic Transistor Sizing

Intro to Verilog

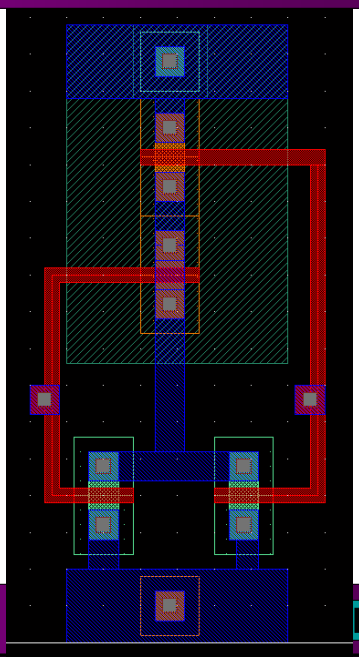
An Example: NOR



- NOR schematic in Composer

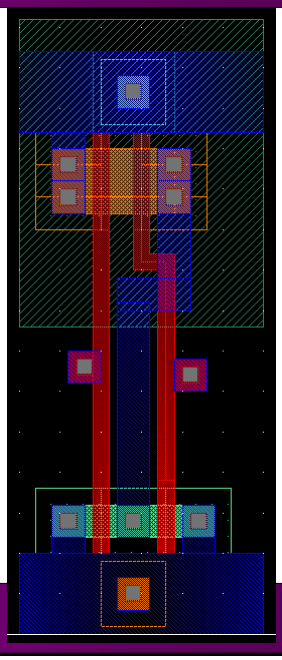
First Layout: Follow Schematic

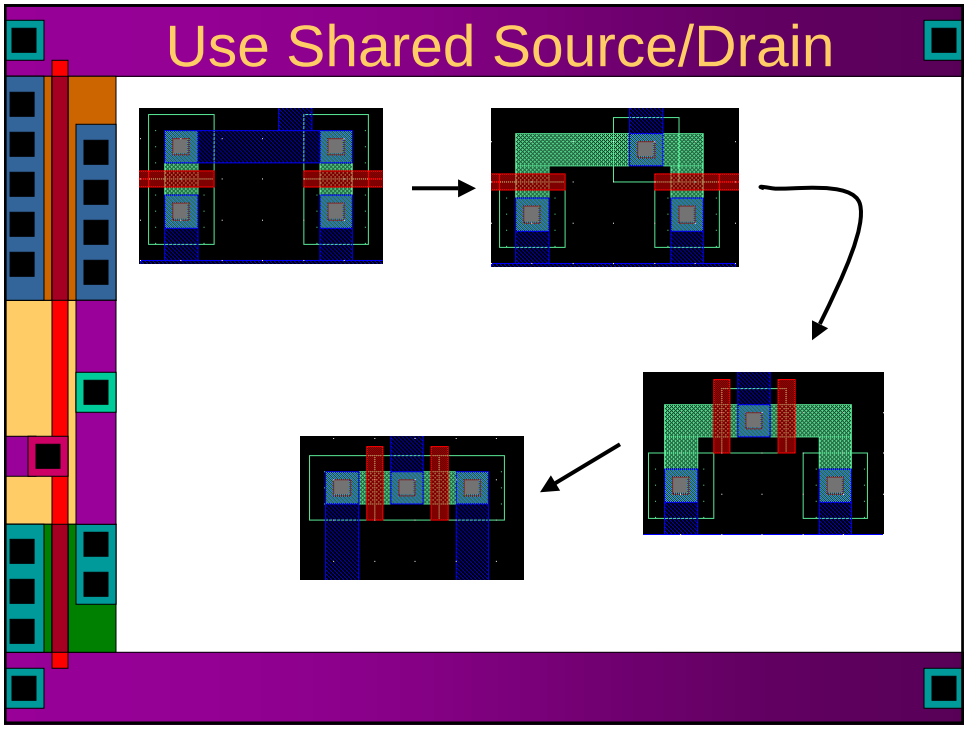
- Note that layout of transistors follows the schematic
  - Two P-types in series pulling up
  - Two N-types in parallel pulling down

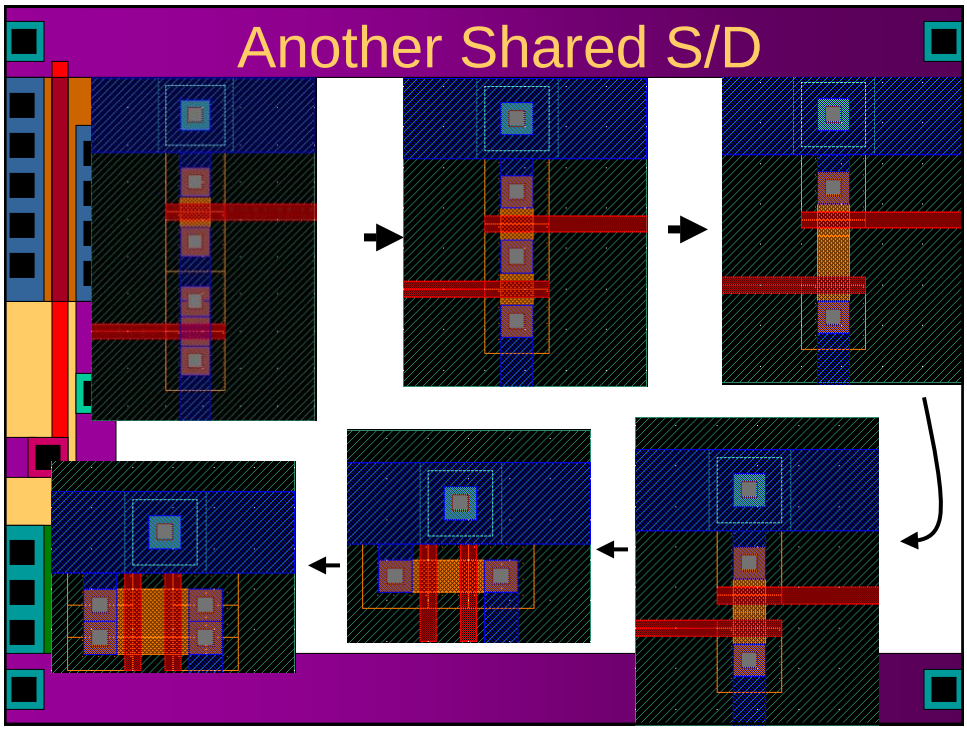


Another Layout: Better?

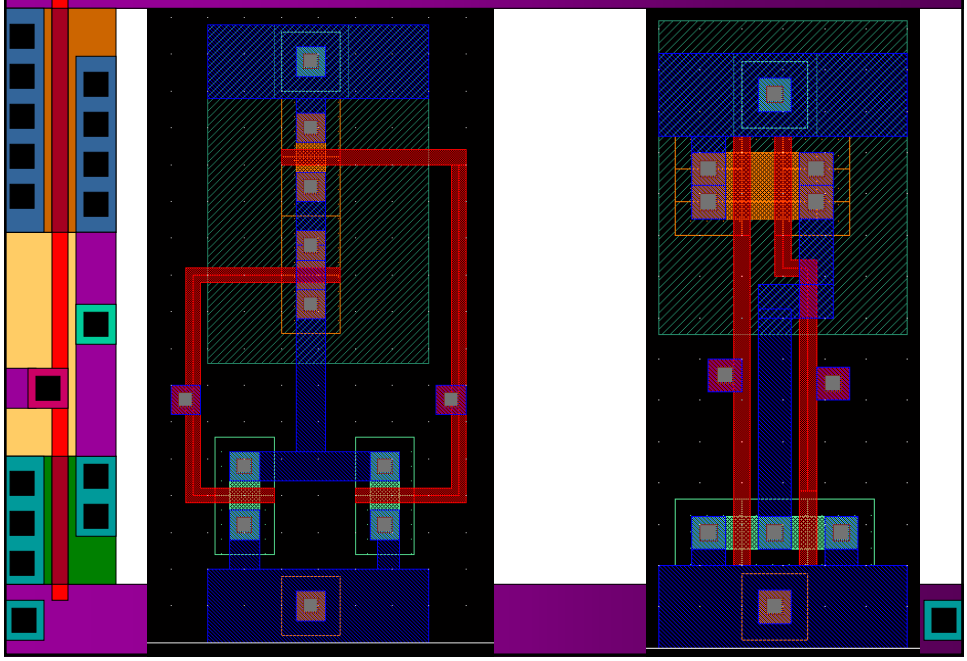
- Same four transistors
  - But, organized a little differently
  - And sized a little differently




Use Shared Source/Drain

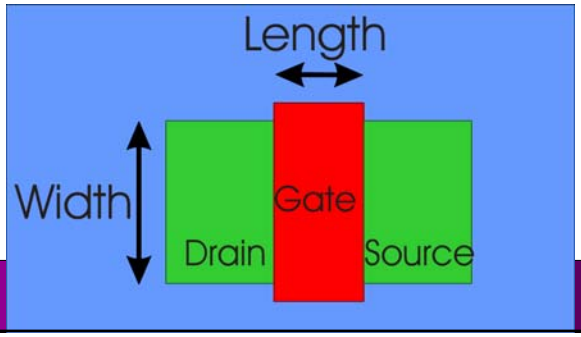

Another Shared S/D

Two NOR Gates



Transistor Sizing

- We'll get into the details later…
- Consider a transistor's Width and Length
  - Current capability is proportional to W/L
  - Length is almost always minimum allowed
  - Change width to change current capability



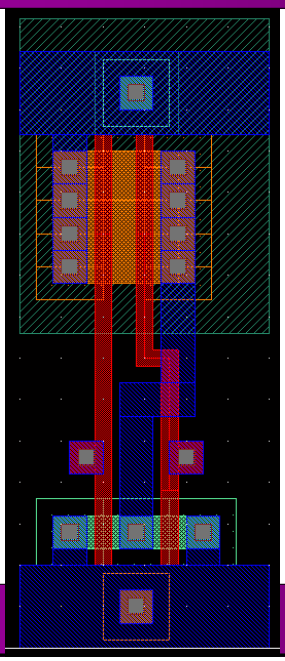
Sizing Rule of Thumb

- Also, P-type is about twice as bad as N-type
  - Has to do with hole mobility vs. electron mobility
- So, make P-types twice as wide as N-types to start with
- Unit size for transistors this semester
  - N-type 1.2u (contact pitch)
  - P-type 2.4u

Sizing Rule of Thumb

- Now multiply each width by n for a series stack of n transistors.
  - Stack of 2, each transistor should be 2x unit size
  - Stack of 3, each transistor should be 3x unit size
- This is because series connections are like increasing the L of the device…
  - Current is proportional to W/L

For example:



- Notice the difference in width…
- This roughly equalizes the current sourcing capability of pull-up and pull-down stacks in this gate

And now for something completely different…

- A little Verilog…
- Big picture: Two main Hardware Description Languages (HDL) out there
  - VHDL
    - Designed by committee on request of the Department of Defense
    - Based on Ada
  - Verilog
    - Designed by a company for their own use
    - Based on C
- Both now have IEEE standards
- Both are in wide use

Data Types

- Possible Values:
  - 0: logic 0, false
  - 1: logic 1, true
  - X: unknown logic value
  - Z: High impedance state
- Registers and Nets are the main data types
- Integer, time, and real are used in behavioral modeling, and in simulation

Registers

- Abstract model of a data storage element
- A reg holds its value from one assignment to the next
  - The value “sticks”
- Register type declarations
  - reg a; // a scalar register
  - reg [3:0] b; // a 4-bit vector register

Nets

- Nets (wires) model physical connections
- They don't hold their value
  - They must be driven by a "driver" (I.e. a gate output or a continuous assignment)
  - Their value is Z if not driven
- Wire declarations
  - wire d; \\ a scalar wire
  - wire [3:0] e; \\ a 4-bit vector wire
- There are lots of types of regs and wires, but these are the basics…

Memories

- Verilog memory models are arrays of regs
- Each element in the memory is addressed by a single array index
- Memory declarations:
  - reg [7:0] imem[0:255]; \\ a 256 word 8-bit memory
  - reg [31:0] dmem[0:1023]; \\ a 1k word memory with 32-bit words

Other types

- Integers:
  - integer i, j; \\ declare two scalar ints
  - integer k[7:0]; \\ an array of 8 ints
- $time - returns simulation time
  - Useful inside $display and $monitor commands…

Number Representations

- Constant numbers can be decimal, hex, octal, or binary
- Two forms are available:
  - Simple decimal numbers: 45, 123, 49039…
  - <size>'<base><number>
  - base is d, h, o, or b
  - 4'b1001 // a 4-bit binary number
  - 8'h2fe4 // an 8-bit hex number

Relational Operators

- A<B, A>B, A<=B, A>=B, A==B, A!=B
  - The result is 0 if the relation is false, 1 if the relation is true, X if either of the operands has any X's in the number
- A===B, A!==B
  - These require an exact match of numbers, X's and Z's included
- !, &&, ||
  - Logical not, and, or of expressions
- {a, b[3:0]} - example of concatenation

Block Structures

- Two types:
  - always // repeats until simulation is done
    begin
    …
    end
  - initial // executed once at beginning of sim
    begin
    …
    end

Example

- Reg [1:0] a,b;

```
initial begin  // only executed once
  a = 2'b01;   // initialize a
  b = 2'b10;   // initialize b
  end
always begin // repeated until simulation done
  #50 a = ~a; // a inverts every 50 time units
  end
always begin // repeated until simulation done
  #100 b = ~b; // b inverts every 100 time units
  end
```

- Note timing control: #50 = delay for 50 time units

Conditional, For

- If (<expr>) <statement> else <statement>
  - else is optional and binds with closest previous if that lacks an else
  - if (index > 0)

```
if (rega > regb)
        result = rega;
else
        result = regb;
```

- For is like C
  - for (initial; condition; step)
  - for (k=0; k<10; k=k+1)

```
statement;
```

Basic Testbench

```
initial
begin
  a[1:0] = 2'b00;
  b[1:0] = 2'b00;
  cin = 1'b0;
$display("Starting...");
#20
$display("A = %b, B = %b, c = %b, Sum = %b, Cout = %b", a, b, cin, sum, cout);
if (sum != 00) $display("ERROR: Sum should be 00, is %b", sum);
if (cout != 0) $display("ERROR: cout should be 0, is %b", cout);
a = 2'b01;
#20
$display("A = %b, B = %b, c = %b, Sum = %b, Cout = %b", a, b, cin, sum, cout);
if (sum != 00) $display("ERROR: Sum should be 01, is %b", sum);
if (cout != 0) $display("ERROR: cout should be 0, is %b", cout);
b = 2'b01;
#20
$display("A = %b, B = %b, c = %b, Sum = %b, Cout = %b", a, b, cin, sum, cout);
if (sum != 00) $display("ERROR: Sum should be 10, is %b", sum);
if (cout != 0) $display("ERROR: cout should be 0, is %b", cout);
$display("...Done");
$finish;
end
```

Nifty Testbench

```
reg [1:0] ainarray [0:4]; // define memory arrays to hold input and result
reg [1:0] binarray [0:4];
reg [2:0] resultsarray [0:4];
integer i;
initial begin
$readmemb("ain.txt", ainarray);  // read values into arrays from files
$readmemb("bin.txt", binarray);
$readmemb("results.txt", resultsarray);
  a[1:0] = 2'b00; // initialize inputs
  b[1:0] = 2'b00;
  cin = 1'b0;
$display("Starting...");
#10 $display("A = %b, B = %b, c = %b, Sum = %b, Cout = %b", a, b, cin, sum, cout);
for (i=0; i<=4; i=i+1) // loop through all values in the memories
 begin
 a = ainarray[i]; // set the inputs from the memory arrays
 b = binarray[i];
 #10 $display("A = %b, B = %b, c = %b, Sum = %b, Cout = %b", a, b, cin, sum, cout);
 if ({cout,sum} != resultsarray[i])
    $display("Error: Sum should be %b, is %b instead", resultsarray[i],sum); // check results array
 end
$display("...Done");
$finish;
end
```